

## Refine Search

### Search Results -

Terms	Documents
L28 and L6	1

Database:

US Pre-Grant Publication Full-Text Database  
 US Patents Full-Text Database  
 US OCR Full-Text Database  
 EPO Abstracts Database  
 JPO Abstracts Database  
 Derwent World Patents Index  
 IBM Technical Disclosure Bulletins

Search:

L29





### Search History

DATE: Tuesday, February 21, 2006    [Printable Copy](#)    [Create Case](#)

Set  
Name Query  
 side by  
 side

Hit  
Count    Set  
                  Name  
                  result  
                  set

DB=PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD; THES=ASSIGNEE; PLUR=YES;  
 OP=OR

L29 L28 and l6

1 L29

L28 L27 and l2

29 L28

L27 l24 or l25 or l26

68 L27

DB=USPT; THES=ASSIGNEE; PLUR=YES; OP=OR

(4598788 | 4834205 | 5267160 | 5076381 | 4768602 | 5019982 | 4730839 |  
 5671143 | 4597462 | 5700073 | 4527654 | 5159553 | 5333058 | 4961144 |  
L26 4828061 | 5001636 | 5001637 | 4836319 | 5313389 | 5742917 | 4572316 |  
 4947327 | 5018070 | 5064013 | 5869753 | 5145022 | 4418780 | 4522417 |  
 5274576 | 5285390 | 4566710 | 4767588 | 4441572 | 5156229 | 4878557 |  
 4552239 | 5097918 | 6161905)! [PN]

38 L26

DB=PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD; THES=ASSIGNEE; PLUR=YES;  
 OP=OR

L25 ('5502639' | '6708088' | '4720790') [ABPN1,NRPN,PN,TBAN,WKU]

6 L25

<u>L24</u>	('5502639' '6708088' '4720790')[URPN]	26	<u>L24</u>
<u>L23</u>	l16 or l17	3	<u>L23</u>
	<i>DB=USPT; THES=ASSIGNEE; PLUR=YES; OP=OR</i>		
<u>L22</u>	('5589815')[URPN]	17	<u>L22</u>
<u>L21</u>	L20 and (tim\$ near2 averag\$)	1	<u>L21</u>
<u>L20</u>	5589815.pn.	1	<u>L20</u>
<u>L19</u>	L8 and (tim\$ near2 averag\$)	0	<u>L19</u>
<u>L18</u>	L17 and (tim\$ near2 averag\$)	0	<u>L18</u>
<u>L17</u>	L16 not (L8 or L15)	3	<u>L17</u>
<u>L16</u>	L13 and (701/36  701/41).ccls.	3	<u>L16</u>
<u>L15</u>	L14 and (tim\$ near2 averag\$)	1	<u>L15</u>
<u>L14</u>	L13 and (steer\$ near2 angle).clm.	19	<u>L14</u>
<u>L13</u>	L12 and (left\$ with right\$ with wheel\$)	25	<u>L13</u>
<u>L12</u>	L11 and accelerat\$ and (yaw near2 rate)	32	<u>L12</u>
<u>L11</u>	L10 and (ratio\$ with (turn\$ or rotat\$) with angle)	132	<u>L11</u>
<u>L10</u>	L9 and (front\$ with rear\$)	886	<u>L10</u>
<u>L9</u>	L2 and @ad<=20021029	1554	<u>L9</u>
<u>L8</u>	L7 and (rotat\$ with angl\$).clm.	1	<u>L8</u>
<u>L7</u>	L6 and (steer\$ near2 angle).clm.	7	<u>L7</u>
<u>L6</u>	L5 and (angl\$ with turn\$ with ratio)	9	<u>L6</u>
<u>L5</u>	L4 and @ad<=20021029	190	<u>L5</u>
<u>L4</u>	L3 and accelerat\$ and (yaw near2 rate)	212	<u>L4</u>
<u>L3</u>	L2 and accelerat\$ and (left\$ near2 wheel) and (right near2 wheel)	383	<u>L3</u>
<u>L2</u>	((steer\$ near2 angle) with sens\$) and (rotat\$ with angle)	1747	<u>L2</u>
	<i>DB=PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD; THES=ASSIGNEE; PLUR=YES; OP=OR</i>		
<u>L1</u>	steer\$ near2 angle	30194	<u>L1</u>

END OF SEARCH HISTORY

## Hit List

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[Generate OACS](#)

**Search Results** - Record(s) 1 through 1 of 1 returned.

☐ 1. Document ID: US 4951207 A

**Using default format because multiple data bases are involved.**

L29: Entry 1 of 1

File: USPT

Aug 21, 1990

US-PAT-NO: 4951207

DOCUMENT-IDENTIFIER: US 4951207 A

TITLE: Method for controlling the front wheel steer angle

DATE-ISSUED: August 21, 1990

**INVENTOR-INFORMATION:**

NAME	CITY	STATE	ZIP CODE	COUNTRY
Furukawa; Yoshimi	Saitama			JP
Takei; Akihiko	Saitama			JP
Ishida; Shinnosuke	Saitama			JP
Oono; Nobuyuki	Saitama			JP

US-CL-CURRENT: 701/42; 180/446

Full	Title	Citation	Front	Review	Classification	Date	Reference	Sequences	Attachments	Claims	KMC	Draw Data
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[Clear](#) [Generate Collection](#) [Print](#) [Fwd Refs](#) [Bkwd Refs](#) [Generate OACS](#)

Terms	Documents
L28 and L6	1

**Display Format:**  [Change Format](#)

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## Hit List

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[Generate OACS](#)

### Search Results - Record(s) 1 through 6 of 6 returned.

☐ 1. Document ID: US 6708088 B2

L25: Entry 1 of 6

File: USPT

Mar 16, 2004

US-PAT-NO: 6708088

DOCUMENT-IDENTIFIER: US 6708088 B2

TITLE: Vehicle behavior control apparatus

Full	Title	Citation	Front	Review	Classification	Date	Reference	Sequences	Attachments	Claims	KWIC	Draw De
------	-------	----------	-------	--------	----------------	------	-----------	-----------	-------------	--------	------	---------

☐ 2. Document ID: US 5502639 A

L25: Entry 2 of 6

File: USPT

Mar 26, 1996

US-PAT-NO: 5502639

DOCUMENT-IDENTIFIER: US 5502639 A

TITLE: Controlling apparatus of steering angle of rear wheels of four-wheel steering vehicle

Full	Title	Citation	Front	Review	Classification	Date	Reference	Sequences	Attachments	Claims	KWIC	Draw De
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☐ 3. Document ID: US 4720790 A

L25: Entry 3 of 6

File: USPT

Jan 19, 1988

US-PAT-NO: 4720790

DOCUMENT-IDENTIFIER: US 4720790 A

TITLE: Apparatus for controlling steer angle of rear wheels of vehicle

Full	Title	Citation	Front	Review	Classification	Date	Reference	Sequences	Attachments	Claims	KWIC	Draw De
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☐ 4. Document ID: US 6708088 B2, US 20020153770 A1, JP 2002316546 A, EP 1256499 A2

L25: Entry 4 of 6

File: DWPI

Mar 16, 2004

DERWENT-ACC-NO: 2003-018490

DERWENT-WEEK: 200420

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TITLE: Vehicle behavior control apparatus for calculating target yaw rate, has target yaw rate calculator which computes target yaw rate based on computed stability factor when turning to left or right

Full	Title	Citation	Front	Review	Classification	Date	Reference	Sequences	Attachments	Claims	KWIC	Draw De
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☐ 5. Document ID: EP 470630 A, KR 9607419 B1, US 5274555 A, EP 470630 A3, EP 470630 B1, DE 69116951 E, US 5502639 A

L25: Entry 5 of 6

File: DWPI

Feb 12, 1992

DERWENT-ACC-NO: 1992-050690

DERWENT-WEEK: 199919

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TITLE: Rear wheels steering angle controlling appts. - controls steering angle of rear wheels of four wheel steering vehicle and provides quick response of electric motor when necessary

Full	Title	Citation	Front	Review	Classification	Date	Reference	Sequences	Attachments	Claims	KWIC	Draw De
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☐ 6. Document ID: EP 165706 A, DE 3564235 G, EP 165706 B, US 4720790 A

L25: Entry 6 of 6

File: DWPI

Dec 27, 1985

DERWENT-ACC-NO: 1986-001263

DERWENT-WEEK: 198601

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TITLE: Vehicle rear wheel steering angle control appts. - steers rear wheels in direction counter to front wheels when steering wheel is operated at high speed

Full	Title	Citation	Front	Review	Classification	Date	Reference	Sequences	Attachments	Claims	KWIC	Draw De
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Clear	Generate Collection	Print	Fwd Refs	Bkwd Refs	Generate OACS
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Terms	Documents
L16 or L17	6

Display Format:

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## The Contents of Case 10691670

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Qnum	Query	DB Name	Thesaurus	Operator	Plural
Q1	steer\$ near2 angle	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD	ASSIGNEE	OR	YES
Q2	((steer\$ near2 angle) with sens\$) and (rotat\$ with angle) Q2 and accelerat\$ and (left\$ near2 wheel) and (right near2 wheel) Q3 and accelerat\$ and (yaw near2 rate) Q4 and @ad<=20021029	USPT	ASSIGNEE	OR	YES
Q3	Q5 and (angl\$ with turn\$ with ratio)	USPT	ASSIGNEE	OR	YES
Q4	Q6 and (steer\$ near2 angle).clm.	USPT	ASSIGNEE	OR	YES
Q5	Q7 and (rotat\$ with angl\$).clm.	USPT	ASSIGNEE	OR	YES
Q6	Q2 and @ad<=20021029	USPT	ASSIGNEE	OR	YES
Q7	Q9 and (front\$ with rear\$)	USPT	ASSIGNEE	OR	YES
Q8	Q10 and (ratio\$ with (turn\$ or rotat\$) with angle) Q11 and accelerat\$ and (yaw near2 rate) Q12 and (left\$ with right\$ with wheel\$)	USPT	ASSIGNEE	OR	YES
Q9	Q13 and (steer\$ near2 angle).clm.	USPT	ASSIGNEE	OR	YES
Q10	Q14 and (tim\$ near2 averag\$)	USPT	ASSIGNEE	OR	YES
Q11	Q13 and 701/36,41.ccls.	USPT	ASSIGNEE	OR	YES

Q17	Q16 not (Q8 or Q15)	USPT	ASSIGNEE	OR	YES
Q18	Q17 and (tim\$ near2 averag\$)	USPT	ASSIGNEE	OR	YES
Q19	Q8 and (tim\$ near2 averag\$)	USPT	ASSIGNEE	OR	YES
Q20	5589815.pn.	USPT	ASSIGNEE	OR	YES
Q21	Q20 and (tim\$ near2 averag\$)	USPT	ASSIGNEE	OR	YES

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**Case Operation** 

## SHOW FILES

File 6:NTIS 1964-2006/Feb W1  
(c) 2006 NTIS, Intl Cpyrght All Rights Res

File 8:EI Compendex(R) 1970-2006/Feb W2  
(c) 2006 Elsevier Eng. Info. Inc.

File 25:Weldasearch-19662006/Jan  
(c) 2006 TWI Ltd

File 36:MetalBase 1965-20060220  
(c) 2006 The Dialog Corporation

File 63:Transport Res(TRIS) 1970-2006/Jan  
(c) fmt only 2006 Dialog

File 65:Inside Conferences 1993-2006/Feb W3  
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File 94:JICST-EPlus 1985-2006/Nov W4  
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File 95:TEME-Technology & Management 1989-2006/Feb W3  
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File 266:FEDRIP 2005/Dec  
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File 2:INSPEC 1898-2006/Feb W2  
(c) 2006 Institution of Electrical Engineers

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```
S (ZERO? (W) POWER? (W) CONTROL?) AND HYBRID? AND PD<=030812
>>>One or more prefixes are unsupported
>>> or undefined in one or more files.
>>>File 25 processing for PD= : PD=030812
>>> started at PD=19080000 stopped at PD=19920106
>>>File 63 processing for PD= : PD=030812
>>> started at PD=DATED stopped at PD=19680517
>>>File 81 processing for PD= : PD=030812
>>> started at PD=19390728 stopped at PD=19920325
      420124 ZERO?
      2534249 POWER?
      4252951 CONTROL?
      126 ZERO? (W) POWER? (W) CONTROL?
      353242 HYBRID?
      1602215 PD<=030812
S2      0 (ZERO? (W) POWER? (W) CONTROL?) AND HYBRID? AND
      PD<=030812
?
```

T S1/3,KWIC/1-2

1/3,KWIC/1 (Item 1 from file: 95)  
DIALOG(R)File 95:TEME-Technology & Management  
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01705484 20021206714

**A transfer-function approach to the analysis and design of zero-power controllers for magnetic suspension systems**

Mizuno, T; Takemori, Y  
Saitama Univ., Urawa, J  
Electrical Engineering in Japan, v141, n2, pp67-75, 2002  
Document type: journal article Language: English  
Record type: Abstract  
ISSN: 0424-7760

**A transfer-function approach to the analysis and design of zero - power controllers for magnetic suspension systems**  
2002

**ABSTRACT:**

A transfer function approach is applied to the analysis and design of zero - power controllers for magnetic suspension systems. The general structures of controllers achieving zero - power control are derived for both current- and voltage-controlled magnetic suspension systems. For the former type...

...the self-sensing suspension also achieves zero-power characteristics automatically. A direct synthesis method for zero - power control is developed based on the analysis. Several experiments are carried out with a single-degree...

1/3,KWIC/2 (Item 2 from file: 95)  
DIALOG(R)File 95:TEME-Technology & Management  
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00949710 I95128108303

**Dynamic analysis of the Maglev system using controlled-PM electromagnets and robust zero-power-control strategy**

(Dynamische Analyse eines Magnetschwebesystems mit geregelten Elektrodauermagneten und robuster Nulleistungsregelstrategie)  
Yeou-Kuang Tzeng; Wang, TC  
Dept. of Electr. Eng., Nat. Tsing Hua Univ., Hsinchu, Taiwan  
INTERMAG '95. 1995 IEEE International Magnetism Conference, 18-21 April 1995, San Antonio, TX, USAIEEE Transactions on Magnetism, v31, n6, PT.2, pp4211-4213, 1995  
Document type: journal article Language: English  
Record type: Abstract  
ISSN: 0018-9464

**Dynamic analysis of the Maglev system using controlled-PM electromagnets and robust zero - power - control strategy**  
1995

**ABSTRACT:**

...presents a rigorous dynamic analysis for a Maglev system with controlled-PM electromagnets and robust zero power control strategy. A variable structure control theory using the new reaching law method is applied to...

IDENTIFIERS: FREQUENCY DOMAIN SYNTHESIS; MAGNETIC LEVITATION; VARIABLE

STRUCTURE SYSTEMS; MAGLEV SYSTEM; CONTROLLED PM ELECTROMAGNETS; ROBUST  
ZERO POWER CONTROL ; DYNAMIC ANALYSIS; VARIABLE STRUCTURE CONTROL  
THEORY; REACHING LAW METHOD; ROBUST CONTROLLER SYNTHESIS; CONTROL VOLTAGE  
CHATTERING...

?

```

S (ZERO? (W) POWER? (W) CONTROL?) AND PD<=030812
>>>One or more prefixes are unsupported
>>> or undefined in one or more files.
>>>File 25 processing for PD= : PD=030812
>>> started at PD=19080000 stopped at PD=19920106
>>>File 63 processing for PD= : PD=030812
>>> started at PD=DATED stopped at PD=19680517
>>>File 81 processing for PD= : PD=030812
>>> started at PD=19390728 stopped at PD=19920325
Processing
      420124 ZERO?
      2534249 POWER?
      4252951 CONTROL?
          126 ZERO? (W) POWER? (W) CONTROL?
      1602215 PD<=030812
S1      2 (ZERO? (W) POWER? (W) CONTROL?) AND PD<=030812
?
```

Application  
Number

SEARCH

IDS Flag Clearance for Application

10691670

IDS  
Information

Content	Mailroom Date	Entry Number	IDS Review	Reviewer
M844	11-07-2003	13	<input checked="" type="checkbox"/>	08-11-2005 00:41:15 IDS CONV
M844	09-30-2004	14	<input checked="" type="checkbox"/>	08-11-2005 00:41:15 IDS CONV

UPDATE